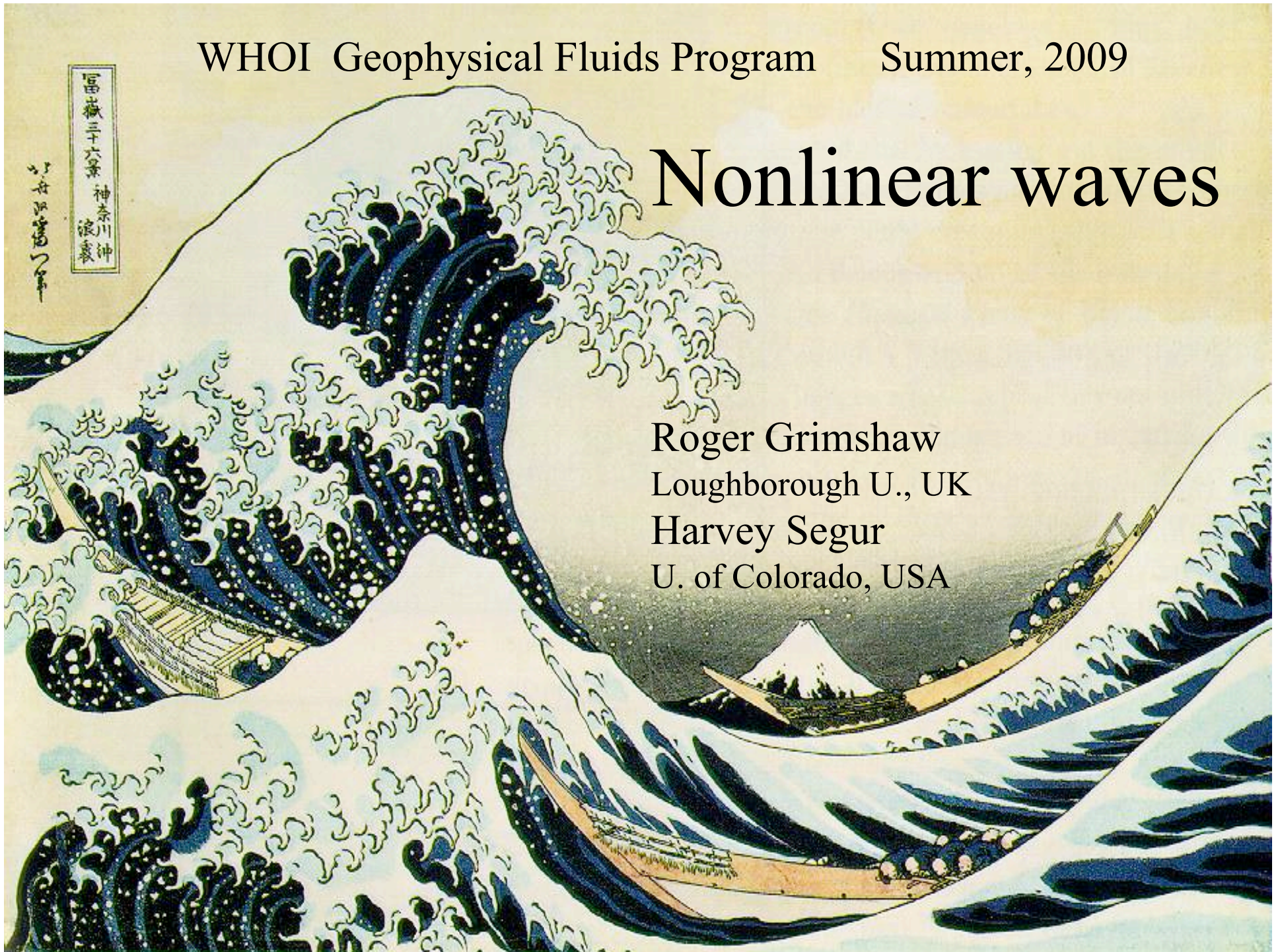


WHOI Geophysical Fluids Program

Summer, 2009

# Nonlinear waves

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Loughborough U., UK  
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U. of Colorado, USA





# Introduction to water waves

## Lecture 1



Q: What's so special about water waves?

# Why study water waves?

a) Woods Hole Oceanographic Institute

b) [For the Program on Nonlinear Waves:](#)

Water waves provide a concrete physical example of a dynamical system rich enough to exhibit many of the mathematical concepts that have been developed in recent years:

linear stability, nonlinear stability

solitons, complete integrability

chaos, sensitive dependence on initial data

singularities, blow-up in finite time

deterministic vs. probabilistic models

c) Water waves evolve on a “human” time-scale, so we can observe many of these concepts in physical experiments

# Introduction to water waves



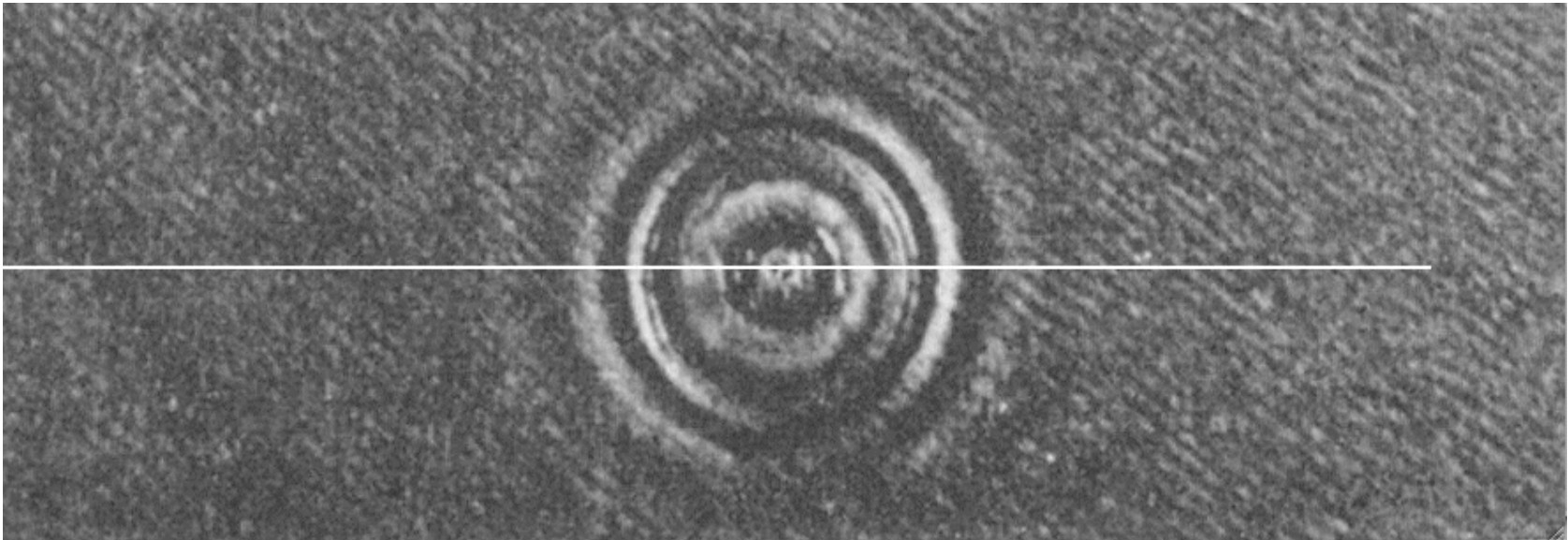
Q: What are “water waves”?

A (for my lectures): Waves in the water that you see or feel at the beach or in a boat  
(sometimes called “surface water waves”)

# Properties of water waves

- Surface water waves have their maximum displacement at the free surface
- Waves propagate, with little dissipation
  - ask a baby in a bath-tub
  - Snodgrass *et al* (1966)
- Approximately periodic:  $0.1 \text{ s} < T < 25 \text{ s}$ .
- Approximate maximum speed:  $c = \sqrt{gh}$
- Water waves are “dispersive”:  
Long waves travel faster than short waves  
(for gravity-induced waves)

Long waves travel faster than short waves (for gravity-induced waves)



from Stoker's *Water Waves* (1957)

# Ocean waves I am ignoring

- **Sound waves** (pressure waves) in water

Speed of sound in water (at 10° C): 1450 m/sec

Speed of 2004 tsunami: < 200 m/sec

Pressure waves create initial conditions for surface waves

- **Internal waves**

Due to variations in fluid density

Period of surface waves: seconds

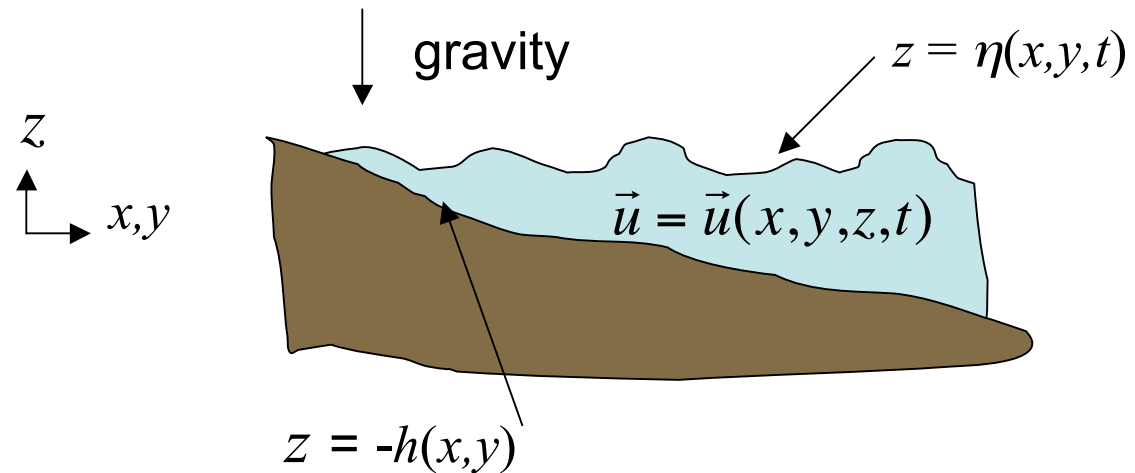
Period of internal waves: hours

- **Inertial waves** (including Rossby waves)

Due to rotation of earth

Period of inertial waves  $\geq$  12 hours

# Derive the governing equations (following Stokes, 1847)



Find:  $\eta(x, y, t)$  – position of free surface, and  
 $\vec{u}(x, y, z, t)$  – fluid velocity, for  
 $-h(x, y) < z < \eta(x, y, t)$ , for  $t > 0$   
and for all  $\{x, y\}$  with  $\eta + h > 0$



# Derive the governing equations (following Stokes, 1847)

## 1. Assumptions

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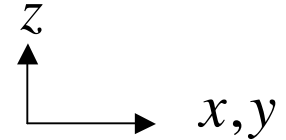
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- [ one more coming... ]

# Derive the governing equations

## 2. Coordinate system(s)

- $[x, y, z]$  denote fixed, laboratory coordinates
- Denote the current location of a fixed fluid particle by



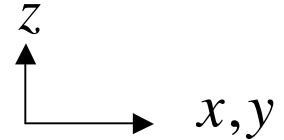
$$\vec{x}(t) = \{x(t), y(t), z(t)\}$$



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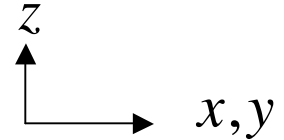
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- Velocity of this fluid particle is  $\vec{u}(\vec{x}, t) = (u, v, w) = \left( \frac{Dx}{Dt}, \frac{Dy}{Dt}, \frac{Dz}{Dt} \right)$
- so  $\left( \frac{D}{Dt} \right)$  means “following the fluid particle”

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–  $\left( \frac{D}{Dt} \right)$  means “following the fluid particle”

– acceleration of the fluid particle (in z-direction) is

$$\frac{Dw}{Dt}(t, \vec{x}(t)) = \frac{\partial w}{\partial t} + \frac{\partial w}{\partial x} \cdot \frac{Dx}{Dt} + \frac{\partial w}{\partial y} \cdot \frac{Dy}{Dt} + \frac{\partial w}{\partial z} \cdot \frac{Dz}{Dt},$$

$$\frac{Dw}{Dt} = \frac{\partial w}{\partial t} + u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z}.$$

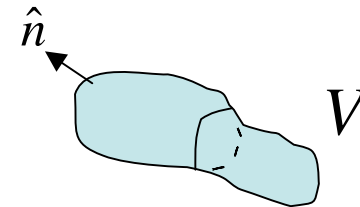
# Derive the governing equations

## 3. Physics

(a) Mass conservation of fluid with constant density

Total mass flow rate from  $V$

$$= \oint_{\partial V} [(\rho)\vec{u} \cdot \hat{n}] ds = 0$$



# Derive the governing equations

## 3. Physics

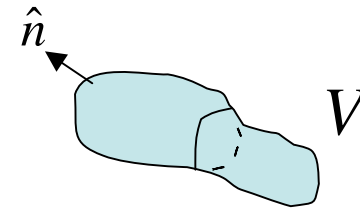
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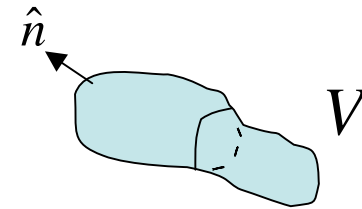
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Divergence theorem  $\rightarrow$

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Valid for all choices of  $V \rightarrow$

$$\boxed{\nabla \cdot \vec{u} = 0}$$



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(b) Aside:

Define vorticity:  $\vec{\omega} = \text{curl}(\vec{u})$

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Suppose (for some reason)  $\vec{\omega} \equiv 0$

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Then  $\nabla \cdot \vec{u} = 0 \iff \nabla^2 \phi = 0$

The velocity of the fluid is found by solving Laplace' eq'n!

What could be simpler?

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## 3. Physics

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What could be simpler?

Q: Is there any reason to believe  $\vec{\omega} \equiv 0$  ?

# Derive the governing equations

## 3. Physics

### (c) Back to reality

Navier-Stokes equations:

$$\rho \frac{D\vec{u}}{Dt} + \nabla p + \rho g \hat{z} = \mu \nabla^2 \vec{u}$$

density    acceleration    pressure    gravity    viscous forces

# Derive the governing equations

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Navier-Stokes equations:

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Neglect viscous forces → Euler's equations

$$\frac{D\vec{u}}{Dt} + \frac{1}{\rho} \nabla p + g \hat{z} = 0$$

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$$\frac{D\vec{u}}{Dt} + \frac{1}{\rho} \nabla p + g \hat{z} = 0$$

Take curl  $\rightarrow$

$$\frac{D\vec{\omega}}{Dt} = \partial_t \vec{\omega} + \vec{u} \cdot \nabla \vec{\omega} = \vec{\omega} \cdot \nabla \vec{u}$$



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Take curl  $\rightarrow$

$$\frac{D\vec{\omega}}{Dt} = \partial_t \vec{\omega} + \vec{u} \cdot \nabla \vec{\omega} = \vec{\omega} \cdot \nabla \vec{u}$$

If  $\vec{\omega} \equiv 0$  at  $t = 0$ , then  $\vec{\omega} \equiv 0$  for all  $t$ .

# Derive the governing equations

## 3. Physics

(d) Last assumption: **irrotational flow**

$$\vec{\omega} \equiv 0 \quad \text{at } t = 0.$$

$$\rightarrow \quad \vec{u} = \nabla \phi, \quad \nabla^2 \phi = 0 \quad \text{everywhere in fluid.}$$

This gives the simplest mathematical model, and the one studied the most. Dropping the assumption gives a more general model. (For internal waves, this is not valid.)

# Derive the governing equations

## 3. Physics

(e) Bernoulli's Law:

Show 
$$\frac{D\vec{u}}{Dt} = \partial_t \vec{u} + \nabla \left( \frac{1}{2} |\vec{u}|^2 \right) - \vec{u} \times \vec{\omega}$$

# Derive the governing equations

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For an irrotational flow,

$$\frac{D\vec{u}}{Dt} = \partial_t \vec{u} + \nabla(\frac{1}{2} |\vec{u}|^2) = \nabla\{\partial_t \phi + \frac{1}{2} |\nabla \phi|^2\}$$

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Euler  $\rightarrow$   $\nabla\{\partial_t \phi + \frac{1}{2} |\nabla \phi|^2 + \frac{p}{\rho} + gz\} = 0$

$\rightarrow$

$$\partial_t \phi + \frac{1}{2} |\nabla \phi|^2 + \frac{p}{\rho} + gz = F(t)$$

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Euler  $\rightarrow$   $\nabla\{\partial_t \phi + \frac{1}{2} |\nabla \phi|^2 + \frac{p}{\rho} + gz\} = 0$

$\rightarrow$   $\partial_t \phi + \frac{1}{2} |\nabla \phi|^2 + \frac{p}{\rho} + gz = F(t) = 0$  in fluid

# Derive the governing equations

## 3. Physics

(f) What happens on the bottom boundary of fluid?

– No flow through the (solid) bottom boundary:

→ on  $z = -h(x, y)$ ,

$$\vec{u} \cdot \nabla \{z + h(x, y)\} = 0 \quad \text{or}$$

$$\partial_z \phi + \nabla \phi \cdot \nabla h = 0 \quad \text{or}$$

$$\partial_n \phi = 0$$

# Derive the governing equations

## 3. Physics

(g) What happens at the free surface?

– With no surface tension and no wind

$$p = p_{air} (= 0) \quad \text{on} \quad z = \eta(x, y, t)$$



# Derive the governing equations

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– With surface tension, usual model:

$$p = p_{air} + \sigma \left( \frac{1}{R_1} + \frac{1}{R_2} \right)$$

↑                      ↑  
const    mean curvature

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$$\rightarrow \boxed{p = 0 - \sigma \left[ \nabla \cdot \left( \frac{\nabla \eta}{\sqrt{1 + |\nabla \eta|^2}} \right) \right]} \quad \text{on} \quad z = \eta(x, y, t).$$

# Derive the governing equations

## 3. Physics

(g) What happens at the free surface?

– 2 boundary conditions on  $z = \eta(x, y, t)$ :

\* Kinematic: a particle on the surface remains there

$$\frac{D}{Dt} \{ \eta(x(t), y(t), t) - z \} = 0$$

→  $\partial_t \eta + \nabla \phi \cdot \nabla \eta = \partial_z \phi$

# Derive the governing equations

## 3. Physics

(g) What happens at the free surface?

– 2 boundary conditions on  $z = \eta(x, y, t)$ :

\* Kinematic: a particle on the surface remains there

$$\frac{D}{Dt} \{z(t) - \eta(x(t), y(t), t)\} = 0$$

→  $\partial_t \eta + \nabla \phi \cdot \nabla \eta = \partial_z \phi$

\* Dynamic: Use surface pressure in Bernoulli's Law

$$\partial_t \phi + \frac{1}{2} |\nabla \phi|^2 + g\eta = \frac{\sigma}{\rho} \nabla \cdot \left\{ \frac{\nabla \eta}{\sqrt{1 + |\nabla \eta|^2}} \right\} \quad (+ \text{ wind?})$$

# Equations of motion

for an irrotational flow, with no forcing from wind:

$$\partial_t \eta + \nabla \phi \cdot \nabla \eta = \partial_z \phi, \quad \text{on } z = \eta(x, y, t)$$

$$\partial_t \phi + \frac{1}{2} |\nabla \phi|^2 + g\eta = \frac{\sigma}{\rho} \nabla \cdot \left\{ \frac{\nabla \eta}{\sqrt{1 + |\nabla \eta|^2}} \right\}, \quad \text{on } z = \eta(x, y, t),$$

$$\nabla^2 \phi = 0 \quad -h(x, y) < z < \eta(x, y, t),$$

$$\partial_z \phi + \nabla \phi \cdot \nabla h = 0, \quad \text{on } z = -h(x, y).$$

# Extra lecture -optional

Monday afternoon (when?):

Start with the nonlinear equations of water waves, linearize them, and explore some fundamental concepts that emerge from the linearized equations.